#### 6.172 Performance Engineering of Software Systems

#### LECTURE 12 Parallel Storage Allocation Julian Shun



#### **REVIEW OF MEMORY-ALLOCATION PRIMITIVES**

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# Heap Storage in C

#### Allocation

void\* malloc(size\_t s); 可能 劳子s *Effect:* Allocate and return a pointer to a block of memory containing at least s bytes.

• Aligned allocation 对有分面乙:与a对南,至少s

void\* memalign(size\_t a, size\_t s); *Effect:* Allocate and return a pointer to a block of memory containing at least s bytes, aligned to a @vectorization multiple of a, where a must be an exact power of 2: also requine

to reduce

0 == ((size\_t) memalign(a, s)) % a

• Deallocation void free(void \*p); *Effect:* p is a pointer to a block of memory returned by malloc() or memalign(). Deallocate the block. © 2008-2018 by the MIT 6.172 Lecturers free -- morse than [ -> double freeing

# **Allocating Virtual Memory**

The mmap() system call can be used to allocate virtual memory by memory mapping: 述中述版本

<pre>void *p =</pre>	mmap(0,	// Don't care where
	size,	<pre>// #bytes</pre>
	PROT_READ   PROT_WRITE,	// Read/write
	MAP_PRIVATE   MAP_ANON,	<pre>// Private anonymous</pre>
A DAY CARLES	-1,	<pre>// no backing file</pre>
	0	<pre>// offset (N/A)</pre>
);		

The Linux kernel finds a contiguous, unused region in the address space of the application large enough to hold size bytes, modifies the page table, and creates the necessary virtual-memory management structures within the OS to make the user's accesses to this area "legal" so that accesses won't result in a segfault.

# Properties of mmap()

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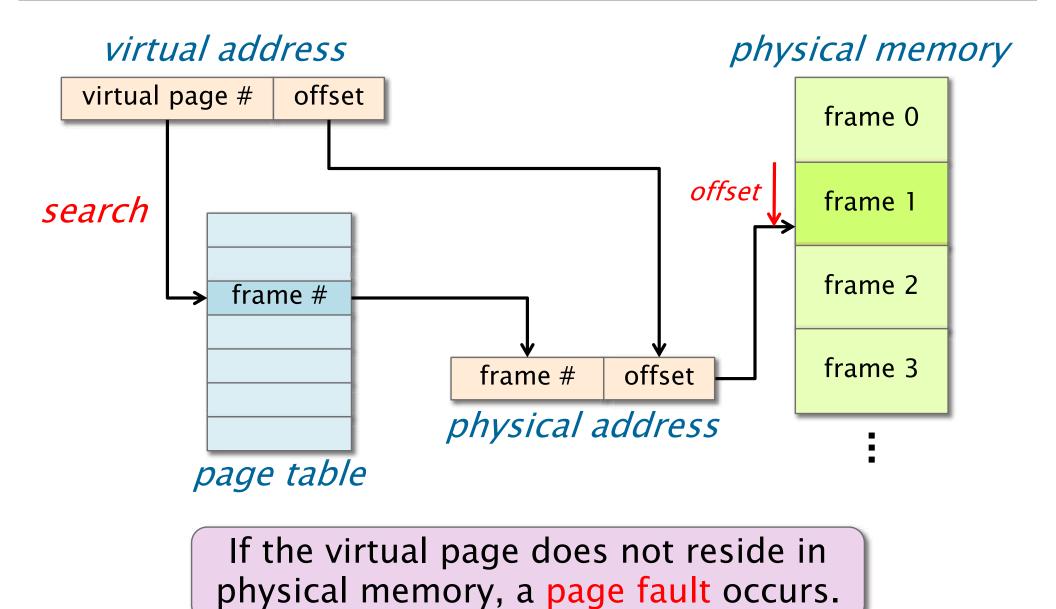
- mmap() is lazy. It does not immediately allocate physical memory for the requested allocation.
- Instead, it populates the page table with entries pointing to a special zero page and marks the page as read only.
- The first write into such a page causes a page fault.
- At that point, the OS allocates a physical page, modifies the page table, and restarts the instruction.
- You can mmap() a terabyte of virtual memory on a machine with only a gigabyte of DRAM.
- A process may die from running out of physical memory well after after the mmap() call.

# What's the Difference...

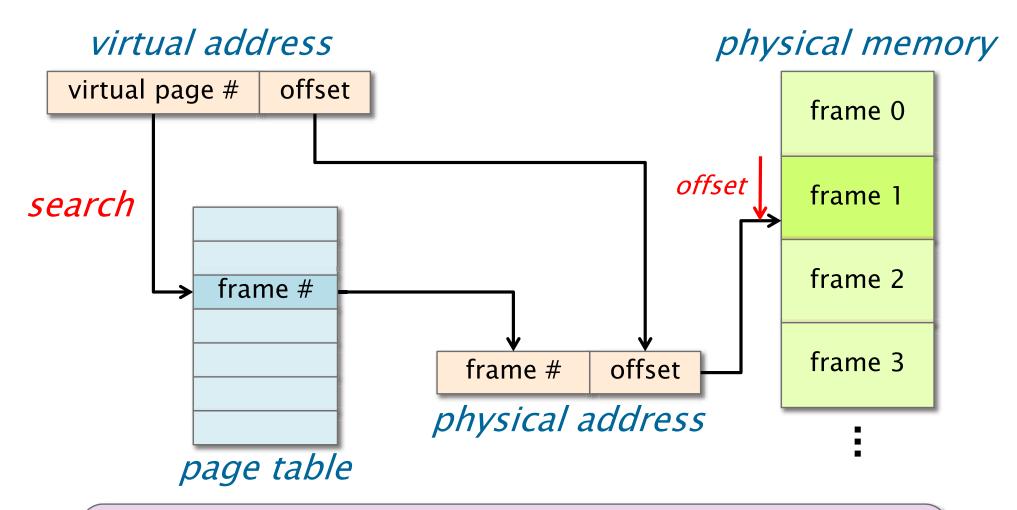
...between malloc() and mmap() used in this way?

- The functions malloc() and free() are part of the memory-allocation interface of the heapmanagement code in the C library.
- The heap-management code uses available system facilities, including mmap(), to obtain memory (virtual address space) from the kernel.
- When necessary, the malloc() implementation invokes mmap() and other system calls to expand the size of the user's heap storage.

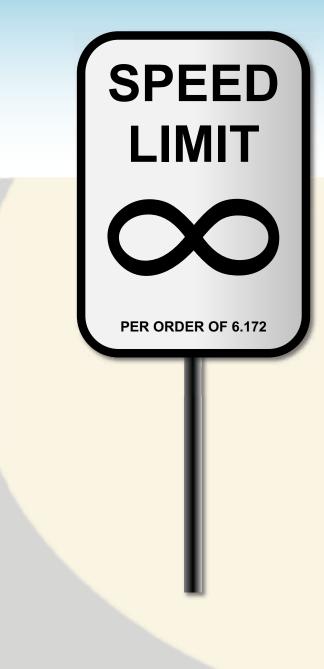
#### **Address Translation**



#### **Address Translation**



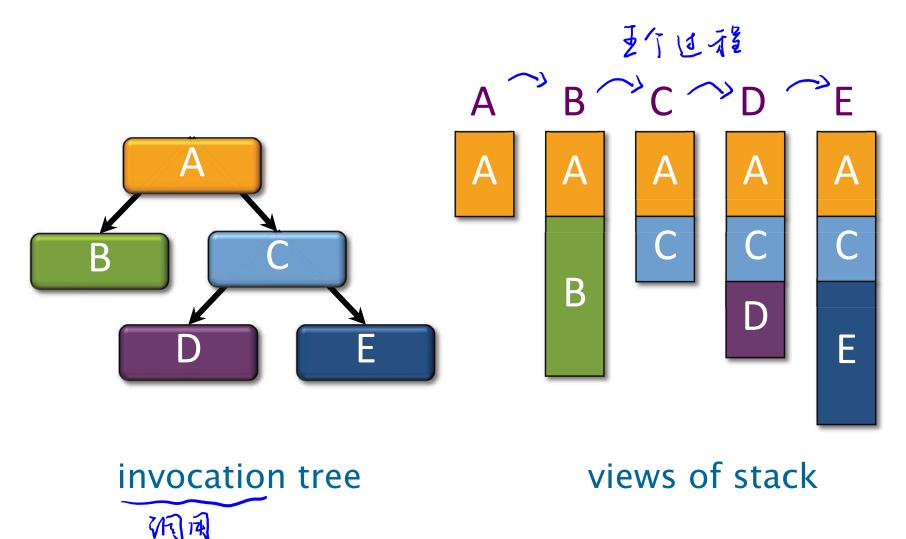
Since page-table lookups are costly, the hardware contains a translation lookaside buffer (TLB) to cache recent page-table lookups.



#### **CACTUS STACKS**

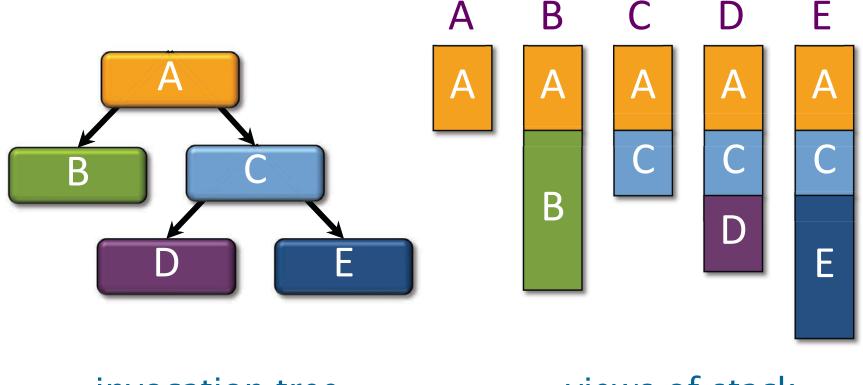
#### **Traditional Linear Stack**

An execution of a serial C/C++ program can be viewed as a serial walk of an invocation tree.



#### **Traditional Linear Stack**

Rule for pointers: A parent can pass pointers to its stack variables down to its children, but not the other way around.

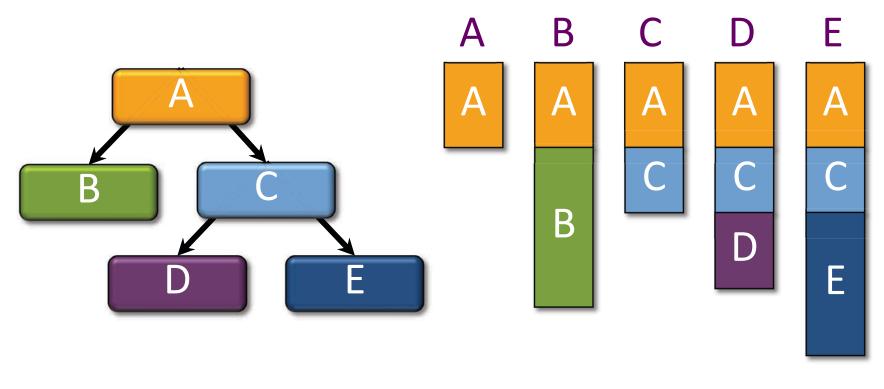


#### invocation tree

views of stack

#### **Cactus Stack**

A cactus stack supports multiple views in parallel.

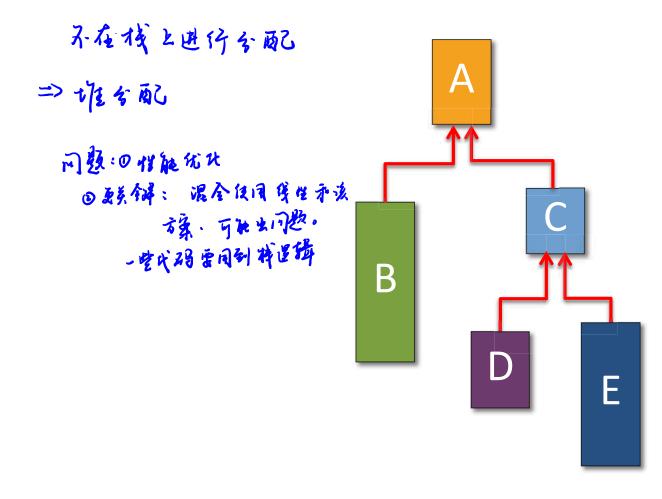


#### invocation tree

views of stack

#### Heap-Based Cactus Stack

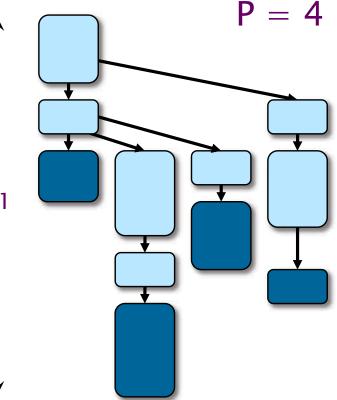
A heap-based cactus stack allocates frames off the heap.



#### Space Bound

**Theorem.** Let  $S_1$  be the stack space required by a serial execution of a Cilk program. The stack space of a P-worker execution using a heap-based cactus stack is at most  $S_P \leq P S_1$ .

Proof. Cilk's work-stealing algorithm maintains the busy-leaves property: Every active leaf frame has a worker executing it. ななかをったまれに S<sub>1</sub>



#### **D&C Matrix Multiplication**

```
分於犯罪
void mm dac(double *restrict C, int n C,
           double *restrict A, int n A,
                                                    Notice that
           double *restrict B, int n B,
           int n)
                                                    allocations of
\{ // C = A * B \}
 assert((n \& (-n)) == n);
                                                    the temporary
 if (n <= THRESHOLD) {</pre>
                                                    matrix D obey a
   mm base(C, n C, A, n A, B, n B, n);
 } else {
                                                    stack discipline.
   double *D = malloc(n * n * sizeof(*D));
   assert(D != NULL);
   #define n D n
   #define X(M,r,c) (M + (r^{*}(n_{\#} M) + c)^{*}(n/2))
   cilk spawn mm dac(X(C,0,0), n C, X(A,0,0), n A, X(B,0,0), n B, n/2);
   cilk_spawn mm_dac(X(C,0,1), n_C, X(A,0,0), n_A, X(B,0,1), n_B, n/2);
   cilk spawn mm dac(X(C,1,0), n C, X(A,1,0), n A, X(B,0,0), n B, n/2);
                                                                          8
   cilk spawn mm dac(X(C,1,1), n C, X(A,1,0), n A, X(B,0,1), n B, n/2);
   cilk_spawn mm_dac(X(D,0,0), n_D, X(A,0,1), n_A, X(B,1,0), n_B, n/2);
   cilk spawn mm dac(X(D,0,1), n D, X(A,0,1), n A, X(B,1,1), n B, n/2);
   cilk_spawn mm_dac(X(D,1,0), n_D, X(A,1,1), n_A, X(B,1,0), n_B, n/2);
              mm_dac(X(D,1,1), n_D, X(A,1,1), n_A, X(B,1,1), n_B, n/2);
   cilk sync;
   m add(C, n C, D, n D, n);
   free(D);
```

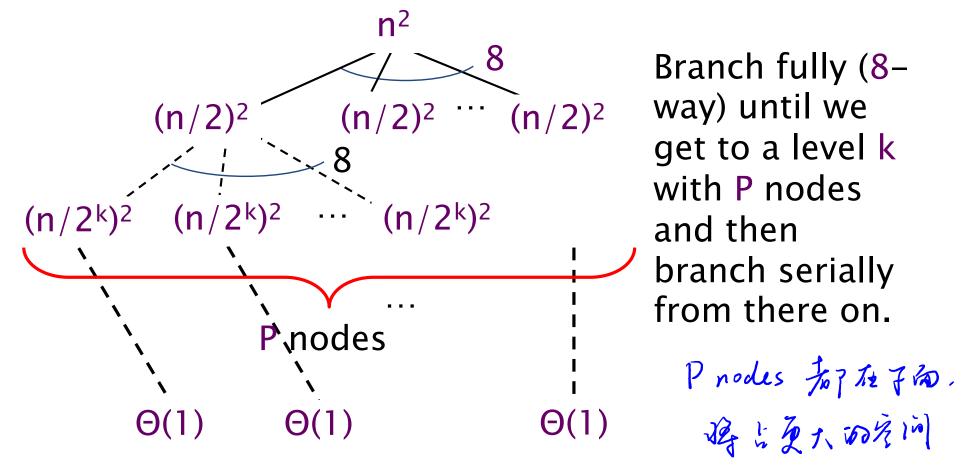
#### Analysis of D&C Matrix Mult.

Work:  $T_1(n) = \Theta(n^3)$ Span:  $T_{\infty}(n) = \Theta(\lg^2 n)$ Space:  $S_1(n) = S_1(n/2) + \Theta(n^2)$   $= \Theta(n^2)$ By the busy-leaves property, we have

 $S_{p}(n) = O(Pn^{2}).$ 

#### We can actually prove a stronger bound.

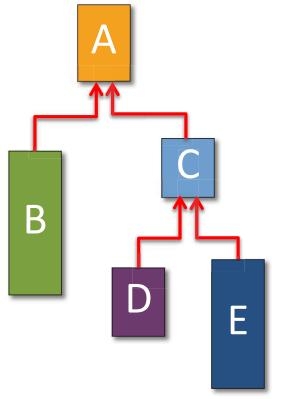
#### **Worst-Case Recursion Tree**



We have  $8^k = P$ , which implies that  $k = \log_8 P = (\lg P)/3$ . The cost per level grows geometrically from the root to level k and then decreases geometrically from level k to the leaves. Thus, the space is  $\Theta(P(n/2^{(\lg P)/3})^2) = \Theta(P^{1/3}n^2)$ .

#### Interoperability

Problem: With heap-based linkage, parallel functions fail to interoperate with legacy and third-party serial binaries. Our implementation of Cilk uses a less space-efficient strategy that preserves interoperability by using a pool of linear stacks.



#### BASIC PROPERTIES OF STORAGE ALLOCATORS

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# **Allocator Speed**

**Definition.** Allocator **speed** is the number of allocations and deallocations per second that the allocator can sustain.

- Q. Is it more important to maximize allocator speed for large blocks or small blocks?
- A. Small blocks! 在小块中分配进展更重要
- Q. Why?
- A. Typically, a user program writes all the bytes of an allocated block. A large block takes so 复身对词藻 much time to write that the allocator time has 写, 会面让 little effect on the overall runtime. In contrast, 此不大 if a program allocates many small blocks, the allocator time can represent a significant overhead.

# Fragmentation

**Definition.** The <u>user footprint</u> is the maximum over time of the number U of bytes in use by the user program (allocated but not freed). The <u>allocator</u>  $\frac{1}{3} \frac{1}{3} \frac$ 

A越接近U越极,因为国产可能用了所有

Remark. A grows monotonically for many 操作系统分配网 allocators.

**Theorem** (proved in Lecture 11). The fragmentation for binned free lists is  $F_V = O(Ig U)$ .

**Remark.** Modern 64-bit processors provide about 2<sup>48</sup> bytes of virtual address space. A big server might have 2<sup>40</sup> bytes of physical memory.

#### **Fragmentation Glossary**

- Space overhead: Space used by the allocator for bookkeeping.
- Internal fragmentation: Waste due to allocating larger blocks than the user requests.
- External fragmentation: Waste due to the inability to use storage because it is not contiguous.
- Blowup: For a parallel allocator, the additional space beyond what a serial allocator would require.

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#### PARALLEL ALLOCATION STRATEGIES 并行会预记标符

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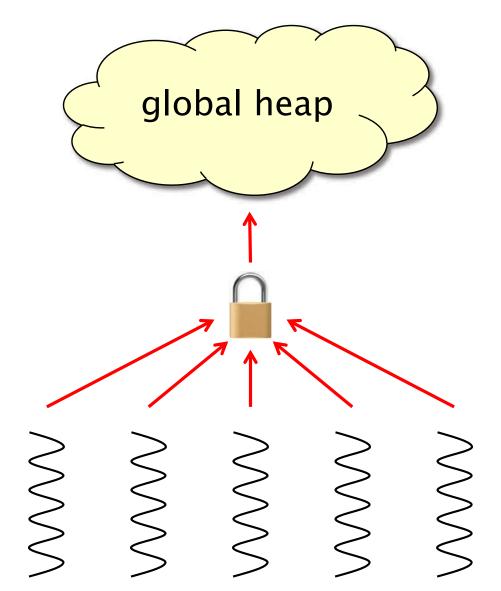
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# Strategy 1: Global Heap

- Default C allocator.
- All threads (processors) share a single heap.
- Accesses are mediated by a mutex (or lock-free synchronization) to preserve atomicity.
- $\odot$  Blowup = 1.
- Slow acquiring a lock is like an L2-cache access.
- Contention can inhibit scalability.



# 可扩展性 Scalability

Ideally, as the number of threads (processors) 燈着钱祥師 grows, the time to perform an allocation or 增加,执行公司 deallocation should not increase.

- eallocation should not increase. 協習同不為議業 • The most common reason for loss of scalability が is lock contention. 積 第月
- Q. Is lock contention more of a problem for large blocks or for small blocks?
- A. Small blocks!
- Q. Why?
- A. Typically, a user program writes all the bytes of an allocated block, making it hard for a thread allocating large blocks to issue allocation requests at a high rate. In contrast, if a program allocates many small blocks in parallel, contention can be a significant issue.

#### **Strategy 2: Local Heaps**

- Each thread allocates out of its own heap.
- No locking is necessary.
- Fast no synchronization.
- Suffers from memory drift: blocks allocated by one thread are freed on another ⇒ unbounded blowup.

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# Strategy 3: Local Ownership

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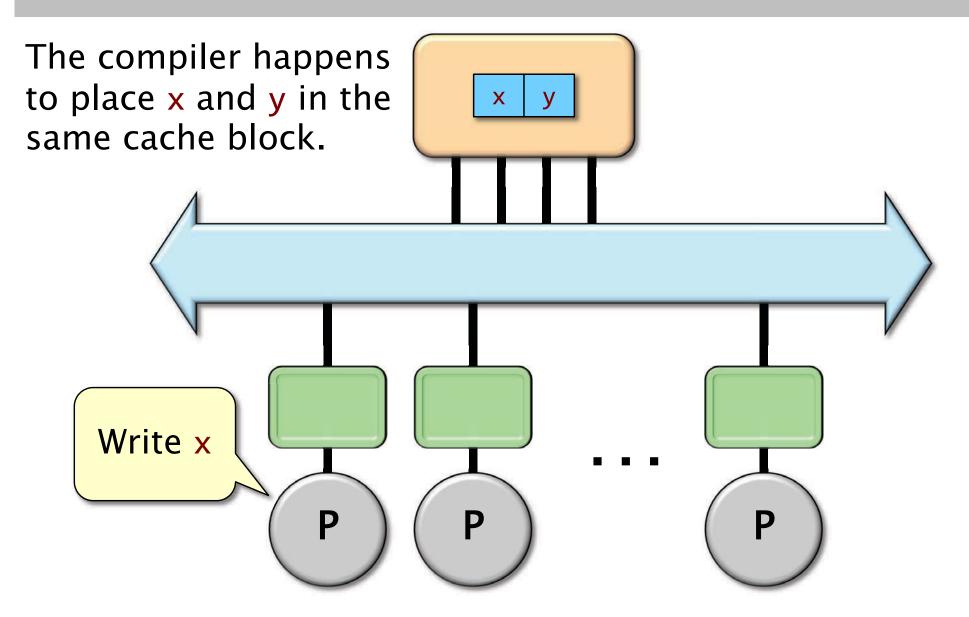
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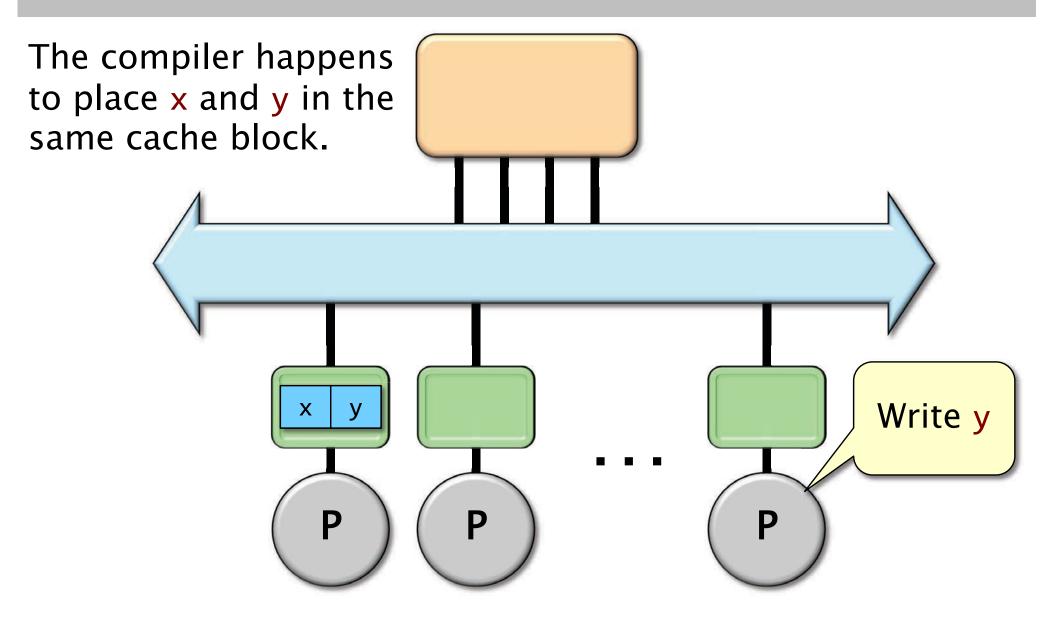
**NNN** 

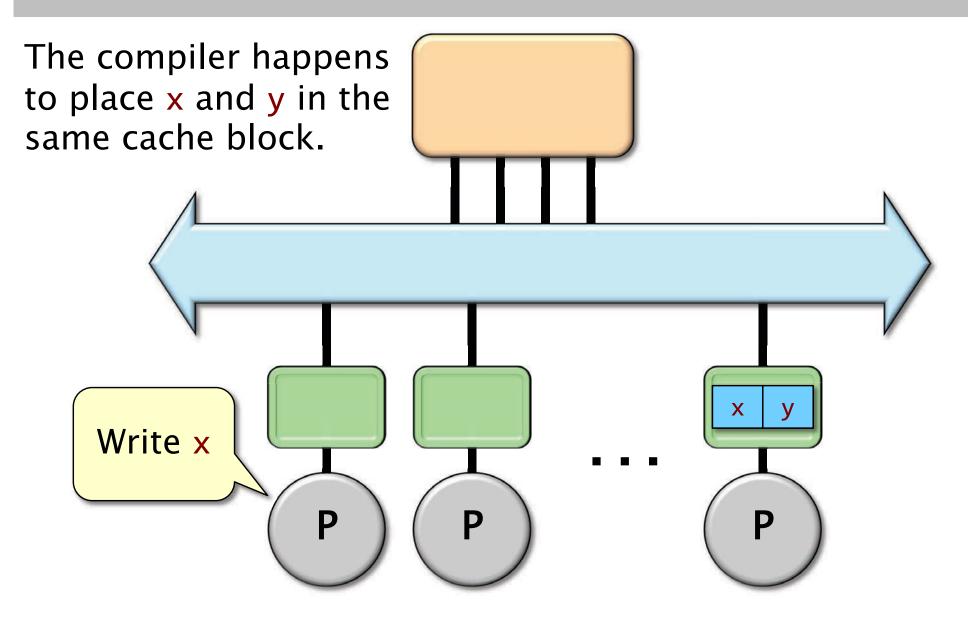
- Each object is labeled with its owner.
- Freed objects are returned to the owner's heap.
- Fast allocation and freeing of local objects.
- Sreeing remote objects requires synchronization.
- $\odot$  Blowup  $\leq$  **P**.
- © Resilience to false 産品な変 sharing.

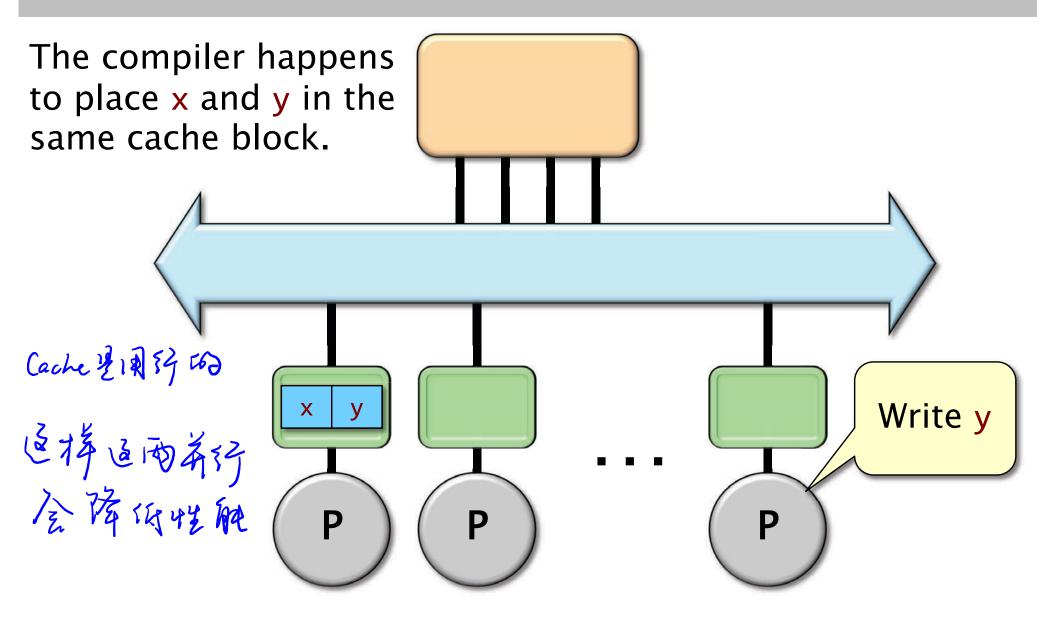


#### **FALSE SHARING**









# How False Sharing Can Occur

A program can induce false sharing having different threads process nearby objects.

• The programmer can mitigate this problem by cache line aligning the object on a cache-line boundary and padding out the object to the size of a cache line, but this solution can be wasteful of space.

An allocator can induce false sharing in two ways:

- Actively, when the allocator satisfies memory requests from different threads using the same cache block. 子順義指述 同己子 援 指 块
- Passively, when the program passes objects lying on the same cache line to different threads, and the allocator reuses the objects' storage after the objects are freed to satisfy requests from those threads.

#### BACK TO PARALLEL HEAP ALLOCATION

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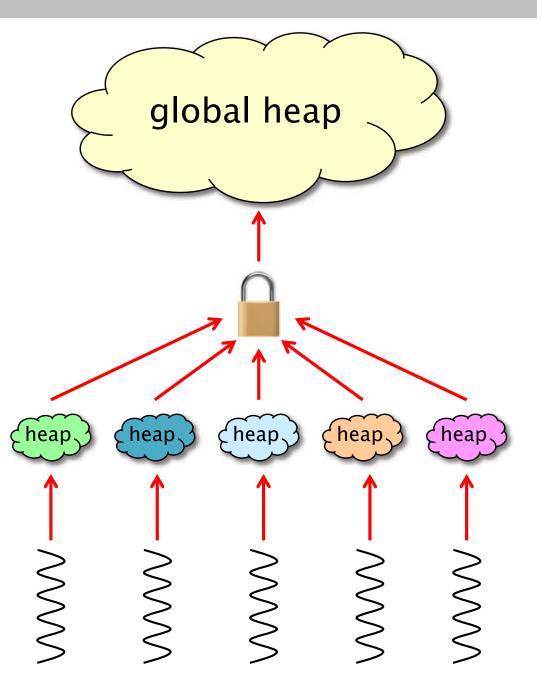
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# **The Hoard Allocator**

- P local heaps.
- 1 global heap.
- Memory is organized into large superblocks of size S.
- Only superblocks are moved between the local heaps and the global heap.
- 🙂 Fast.
- 🙂 Scalable.
- ③ Bounded blowup.
- Resilience to false sharing.



#### **Hoard Allocation**

Assume without loss of generality that all blocks are the same size (fixed-size allocation).

```
x = malloc() on thread i
```

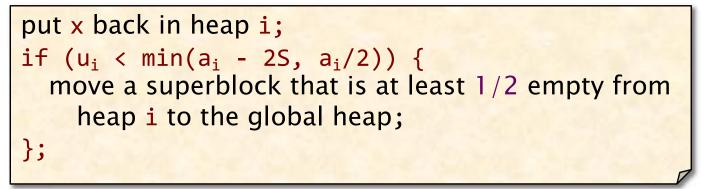
```
if (there exists a free object in heap i) {
    x = an object from the fullest nonfull superblock in i's heap;
} else {
    if (the global heap is empty) {
        B = a new superblock from the OS;
    } else {
        B = a superblock in the global heap;
    }
    set the owner of B to i;
    x = a free object in B;
}
return x;
```

#### **Hoard Deallocation**

Let  $u_i$  be the in-use storage in heap i, and let  $a_i$  be the storage owned by heap i. Hoard maintains the following invariant for all heaps i:

 $u_i \ge min(a_i - 2S, a_i/2),$ where S is the superblock size.

free(x), where x is owned by thread i:



# Hoard's Blowup

Lemma. The maximum storage allocated in global heap is at most maximum storage allocated in local heaps.

**Theorem.** Let U be the user footprint for a program, and let A be Hoard's allocator footprint. We have

 $A \leq O(U + SP)$ ,

and hence the blowup is

A/U = O(1 + SP/U).

**Proof.** Analyze storage in local heaps. Recall that  $u_i \ge \min(a_i - 2S, a_i/2)$ . First term: at most 2S unutilized storage per heap for a total of O(SP). Second term: allocated storage is at most twice the used storage for a total of O(U).

# **Other Solutions**

jemalloc is like Hoard, with a few differences:

- jemalloc has a separate global lock for each different allocation size.
- jemalloc allocates the object with the smallest address among all objects of the requested size.
- jemalloc releases empty pages using

madvise(p, MADV\_DONTNEED, ...) , which zeros the page while keeping the virtual address valid.

• jemalloc is a popular choice for parallel systems due to its performance and robustness.

SuperMalloc is an up-and-coming contender. (See paper by Bradley C. Kuszmaul.)

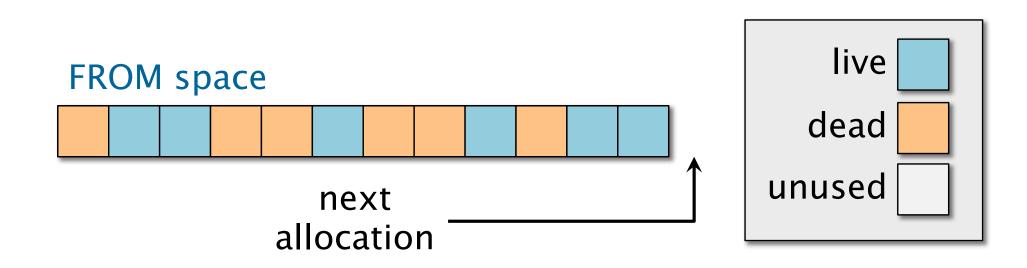
### **Allocator Speeds**

Allocator	SLOC	32 threads
Default	6,281	0.97 M/s
Hoard	16,948	17.1 M/s
jemalloc	22,230	38.2 M/s
SuperMalloc	3,571	131.7 M/s

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#### **GARBAGE COLLECTION**

# **Copying Garbage Collector**



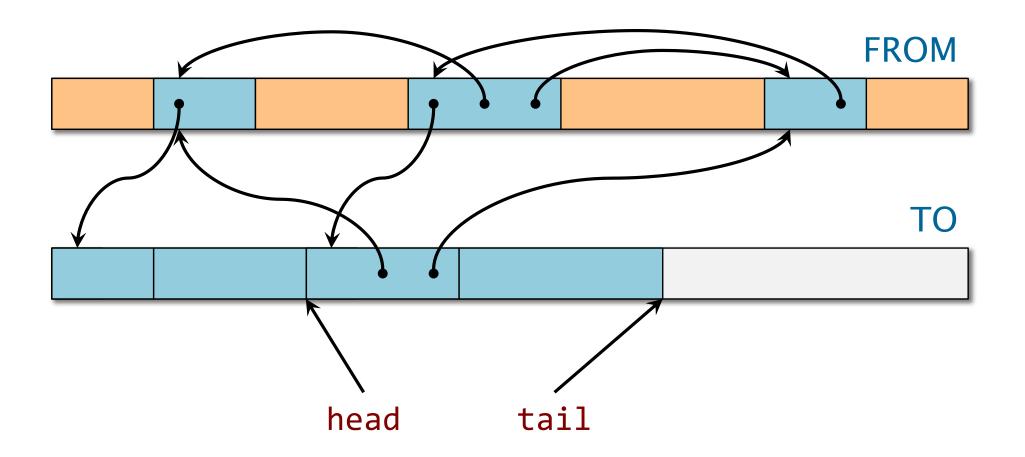
When the FROM space is "full," copy live storage using BFS with the TO space as the FIFO queue.

TO space

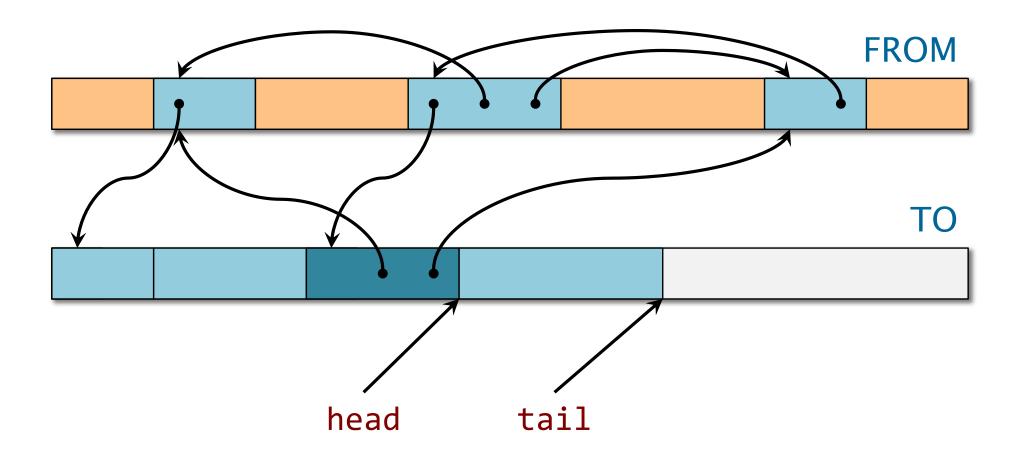
# **Updating Pointers**

Since the FROM address of an object is not generally equal to the TO address of the object, pointers must be updated.

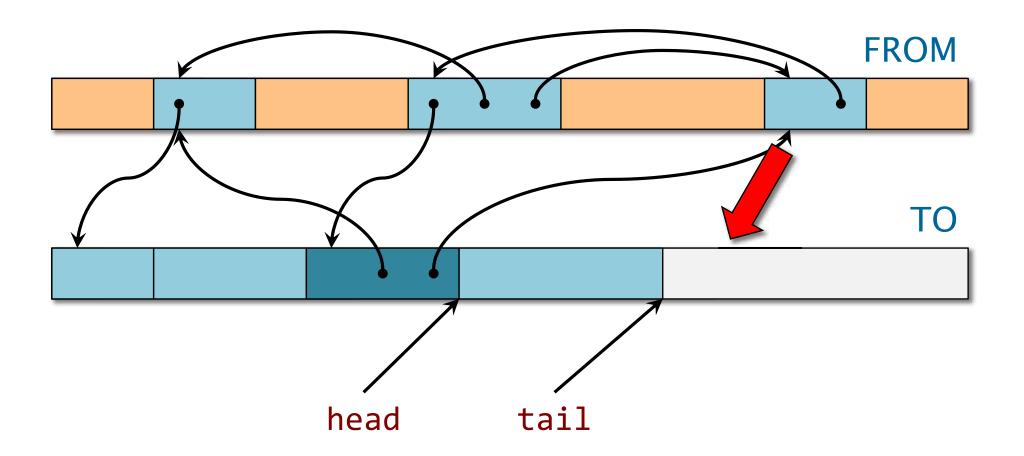
- When an object is copied to the TO space, store a forwarding pointer in the FROM object, which implicitly marks it as moved.
- When an object is removed from the FIFO queue in the TO space, update all its pointers.



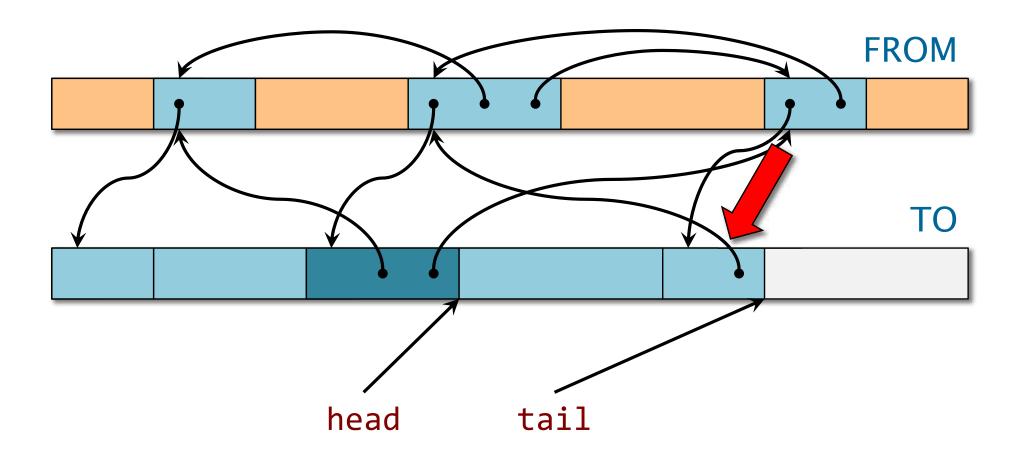
Remove an item from the queue.



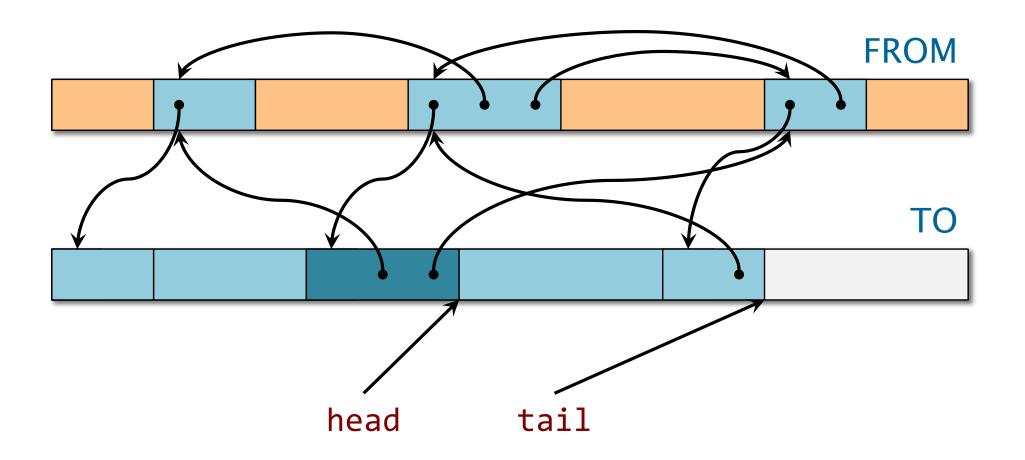
Remove an item from the queue.



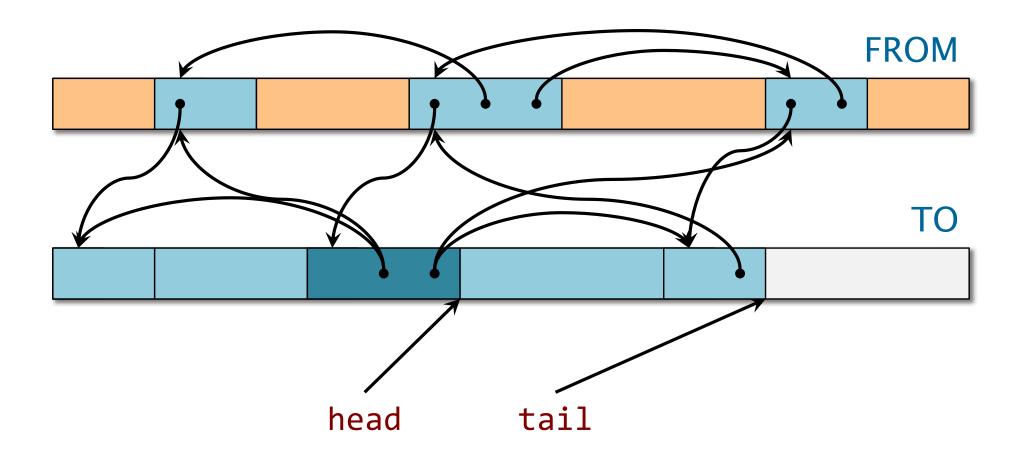
Enqueue adjacent vertices.



Enqueue adjacent vertices. Place forwarding pointers in FROM vertices.



Update the pointers in the removed item to refer to its adjacent items in the TO space.



Update the pointers in the removed item to refer to its adjacent items in the TO space.

# **Types of Garbage Collectors**

Stop-the-world collector バ 必 停止 非清 加 • Program pauses once in a while and garbage

- Program pauses once in a while and garbage collector (GC) does work across all of memory
- High program pause times



Incremental collector

 Collector cleans up a small part of memory every time it executes

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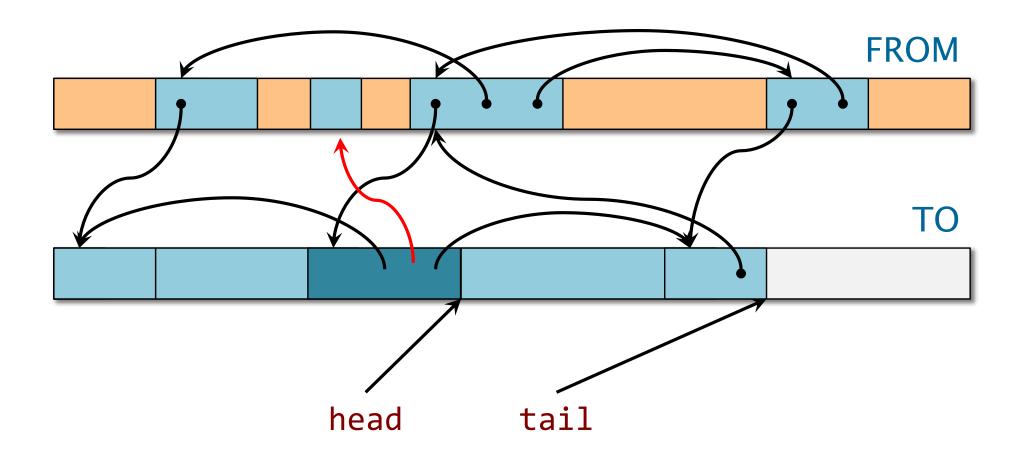
• Low program pause times



# **Running Collector with Program**

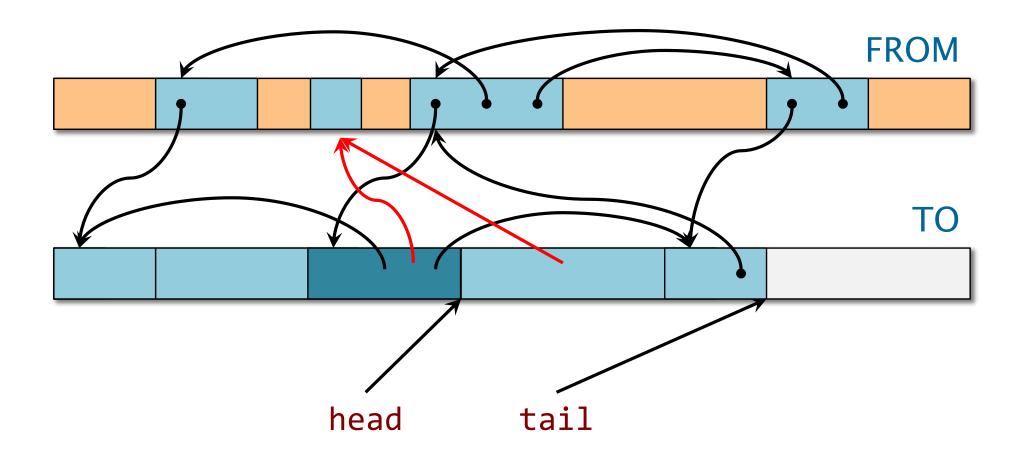
- Incremental version of copying collector.
- When it is time to collect, application program and garbage collector take turns running.

# **Running Collector with Program**



If an object O already dequeued in BFS gains a reference to another object O', the BFS may not find O' and it will be freed.

# **Running Collector with Program**



If an object O already dequeued in BFS gains a reference to another object O', the BFS may not find O' and it will be freed.

# **Baker's Algorithm**

- Program follows forward pointer if there is one.
- Whenever the program accesses an object not in the TO space, mark object as explored and copy it over to the TO space.
- Whenever the program allocates an object, put it in the TO space.
- Requires a read barrier to intercept every read with a check, which is expensive.
- This algorithm is conservative in that it does not necessarily collect all garbage. Why?

# Nettles-O'Toole Algorithm

- Program works only in FROM space until garbage collection is finished.
- Replicates the objects by keeping mutations to FROM-space objects in a log.
- Garbage collector applies the mutations to corresponding TO-space objects.
- Requires a write barrier to log mutations on every write
  - This is expensive, but writes are usually much less frequent than reads.
- Is this algorithm conservative?

# Garbage Collection Glossary

- Stop-the-world: Garbage collector does all of its work across memory while pausing program.
- Incremental: Garbage collector runs incrementally, allowing pause times to be bounded.
- Parallel: Multiple collector threads are running simultaneously.
- Concurrent: At least one program thread and one collector thread are running simultaneously.

# Parallel and Concurrent GC

- Based on Nettles-O'Toole algorithm
- High–level idea
  - Use per-processor local stacks for search
  - Maintain a shared stack for load balancing
     Processors periodically transfer objects between local and shared stack
  - Use synchronization primitives (test-and-set and fetch-and-add) to manage concurrent accesses

See "On Bounding Time and Space for Multiprocessor Garbage Collection" (PLDI 1999), and "A Parallel, Real-Time Garbage Collector" (PLDI 2001) by Cheng and Blelloch

#### Summary

- malloc() vs. mmap()
- Cactus stacks
- Cilk space bound of  $S_P \leq P \: S_1$  and better bound for matrix multiply
- Parallel allocation strategies: global heap, local heaps, local ownership
- Incremental garbage collection
- Parallel and concurrent garbage collection



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